Set Orders

DC Input

p. 10

Features

Low vibration

Thanks to their low vibration mode, SANMOTION F2 stepping drivers can smoothly operate stepping motors even at low resolution settings such as full-step and half-step modes. Vibrations can be suppressed regardless of the host controller.



Microstepping drive

Resolution settings up to 16 subdivisions of the full step angle can be used, enabling smooth equipment operation with low vibration.

RoHS

IP65-Rated Stepping Motors

How to Read Specifications

Unipolar DC input driver (model: US1D200P10) and stepping motor

2	Sizo	Motor size		28 mm sq. (1.8°	full step angle)	42 mm sq. (1.8° full step angle)				
	3126	Motor length		32 mm	51.5 mm	33 mm	39 mm			
3	Single	Set order no.		DU14S281S	DU14S285S	DU15S421S	DU15S422S			
	shaft	Motor model no.		SH2281-5271	SH2285-5271	SF2421-12U41	SF2422-12U41			
	Dual shaft	Set order no.		DU14S281D	DU14S285D	DU15S421D	DU15S422D			
		Motor model no.		SH2281-5231	SH2285-5231	SF2421-12U11	SF2422-12U11			
4	Holding to	N·m otor inertia × 10 ⁻⁴ kg·m ² ated current A/phase fotor mass ⁽¹⁾ kg Illowable thrust load N		0.055	0.115	0.22	0.33			
6	Rotor inert			0.01	0.022	0.031	0.046			
6	Rated curre			1	1	1.2	1.2			
0	Motor mas			0.11	0.2	0.23	0.3			
8	Allowable			3	3	10	10			
9	Allowable radial load ⁽²⁾ N		N	42	49	39	37			
	(1) For the di	river mass, see >p. 26	(2) Load is exerted	to the shaft end.						

Characteristics



1 Model number of the driver included in the set.

- 2 Flange size and length of the stepping motor included in the set. The full step angle is the angle at which the motor rotates with each pulse in full step mode. In half step mode, the motor rotates by a half the full step angle with each pulse.
- 3 The set order number and the model number of the stepping motor included in the set. The model number varies depending on whether the motor's shaft is single shaft or dual shaft.
- 4 This is the maximum torque that is generated when the stepping motor is rotated by exerting an external force on the shaft at 2-phase excitation at the rated current.
- 5 This is the moment of inertia of the rotor.
- 6 This is the rated current that flows to the motor winding.
- This is the mass of the stepping motor.
- 8 This is the maximum allowable load to the shaft in the axial direction. Take care not to exceed this limit.
- 9 This is the maximum allowable load to the shaft in the direction perpendicular to the axial direction. Take care not to exceed this limit.
- 10 This graph shows the relationship between the pulse rate (frequency), motor speed, and torque. The driver's input current is shown in addition to the torque. Characteristics in full step mode is shown in red, and in half step mode is shown in blue.
- 11 The pull-out torque is the maximum torque in which synchronized operation with command pulses can be maintained. If a torque that exceeds this value is applied to the stepping motor, it will be unable to syn-

chronize with command pulses. Thus, when selecting a motor, you should allow for a torque margin of 1.4 to 2 times, in order to avoid step-out.

Pulse rate (kpulses/s)

Full step 😐

Full step

10

1000 2000 3000 5000 Speed (min⁻¹) 1000 2000 3000 5000

Input current (with load)

Pull-out torque

36 VDC

0.

0.08

Ê 20.06

anb.0.04

0.02

Full step

Half step

Ω

´ N 1

100

100

Half step <

Half step

10

9

7

5

4

3

100

Input current (A)

- 😢 This graph shows the current value of the power supply powering the driver.
 - The red and blue dashed lines show the source current value when there is no load (motor by itself).
 - The red and blue dotted lines show the source current value when the maximum torque is applied to the stepping motor (with a load).

The required power supply capacity (W) is calculated from this graph.

¹³The red- and blue-colored dots in the lower part of the graph show the upper limit for the maximum starting pulse rate (fs) of the stepping motor by itself (with no load). Values in full step mode is shown in red, and in half step mode is shown in blue. The stepping motor will not operate normally if it is started using pulse rates that exceed these values. For this reason, it is necessary to start the stepping motor using pulse rates that are lower than these values. The maximum starting pulse rate with loads (fL) can be determined using the expression below.



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DC Input Set Orders

Unipolar/Bipolar



Items included in a set... >p. 12 Specifications/Characteristics... >p. 13 to 21 Motor dimensions...>p. 22 to 23 Motor specifications...>p. 24 Driver dimensions... ▶ p. 26 Driver specifications... ▶ p. 26

Items included in a set RoHS =

Driver Terminal block type



Unipolar Model no.: US1D200P10 Input voltage: 24/36 VDC Bipolar Model no.: BS1D200P10 Input voltage: 24/36 VDC

- · The Instruction Manual is available for download from our website.
- · Drivers are available for separate purchase. Connector-type drivers are also available. Contact us for details.
 - Motor

c Sus (Only for 56 mm sq. motors)

Unipolar motor sizes: 28 mm sq., 42 mm sq., 56 mm sq. Bipolar motor sizes: 28 mm sq., 42 mm sq., 50 mm sq., 56 mm sq., 60 mm sq.

Cable with connectors

Supplied only with connector-type motors

System Configuration



e.g., The model number shown below is a set of a DC input driver (US1D200P10) and a motor (SM2561C20U41). The motor's specifications are: 56 mm sq. size, 41.8 mm length, and single shaft.



Items Included in a Set These sets include a driver, motor, and motor cable with connectors.

Motors marked with () are lead-type motors. 300 mm or longer leads are attached to the motor. Motors marked with (2) are connector-type motors. The following motor cables with connectors are included.

Unipolar Bundled driver model no.: US1D200P10

	Single shaft				Dual shaft					D (1	Dawa	
Motor size		Items included in a set				Items included in a set			Full ston	Kated	rage	
1010101 3120	Set order no.	Motor model no.		Motor cable with connectors model no.	Set order no.	Motor model no.		Motor cable with connectors model no.	angle	[A/phase]	Specifi- cations	Dimen- sions
20 mm ca	DU14S281S	SH2281-5271	L	-	DU14S281D	SH2281-5231	L	-	1.8°	1	p. 13	p. 22
20 11111 54.	DU14S285S	SH2285-5271	L	-	DU14S285D	SH2285-5231	L	-	1.8°	1	p. 13	p. 22
	DU15S421S	SF2421-12U41	C	4835774-1	DU15S421D	SF2421-12U11	C	4835774-1	1.8°	1.2	p. 13	p. 22
	DU15S422S	SF2422-12U41	C	4835774-1	DU15S422D	SF2422-12U11	C	4835774-1	1.8°	1.2	p. 13	p. 22
	DU15S423S	SF2423-12U41	C	4835774-1	DU15S423D	SF2423-12U11	C	4835774-1	1.8°	1.2	р. 14	p. 22
42 mm sq.	DU15S424S	SF2424-12U41	C	4835774-1	DU15S424D	SF2424-12U11	C	4835774-1	1.8°	1.2	р. 14	p. 22
	DU15S141S	SH1421-0441	L	-	DU15S141D	SH1421-0411	L	-	0.9°	1.2	р. 14	p. 22
	DU15S142S	SH1422-0441	L	-	DU15S142D	SH1422-0411	L	-	0.9°	1.2	р. 14	p. 22
	DU15S144S	SH1424-0441	L	-	DU15S144D	SH1424-0411	L	-	0.9°	1.2	p. 15	p. 22
	DU16M711S	SM2561C20U41	С	4837798-1	DU16M711D	SM2561C20U11	С	4837798-1	1.8°	2	р. 15	p. 23
E6 mm og	DU16M712S	SM2562C20U41	С	4837798-1	DU16M712D	SM2562C20U11	С	4837798-1	1.8°	2	р. 15	p. 23
oo min sq.	DU16M713S	SM2563C20U41	С	4837798-1	DU16M713D	SM2563C20U11	С	4837798-1	1.8°	2	p. 15	p. 23
	DU16M714S	SM2564C20U41	С	4837798-1	DU16M714D	SM2564C20U11	С	4837798-1	1.8°	2	p. 16	p. 23

• Motor cable with connectors Note: Included with connector-type motors only

For 42 mm sq. unipolar motors (Model no.: 4835774-1)





(Model no.: 4837798-1)

Dimensions Unit: mm

Leads UL 1430, 22 AWG

For 56 mm sq. unipolar motors

Bipolar Bundled driver model no.: BS1D200P10

	Single shaft				Dual shaft					Deted	Paga	
Motor size		Items included in a set				Items included in a set			FUII sten	Kated	raye	
10101 3120	Set order no.	Motor model no.		Motor cable with connectors model no.	Set order no.	Motor model no.		Motor cable with connectors model no.	angle	[A/phase]	Specifi- cations	Dimen- sions
29 mm ca	DB14S281S	SH2281-5771	L	-	DB14S281D	SH2281-5731	L	-	1.8°	1	p. 17	p. 22
20 mm sy.	DB14S285S	SH2285-5771	L	-	DB14S285D	SH2285-5731	L	-	1.8°	1	p. 17	p. 22
	DB14S421S	SF2421-10B41	C	4835775-1	DB14S421D	SF2421-10B11	C	4835775-1	1.8°	1	p. 17	p. 22
	DB14S422S	SF2422-10B41	C	4835775-1	DB14S422D	SF2422-10B11	С	4835775-1	1.8°	1	р. 17	p. 22
	DB14S423S	SF2423-10B41	C	4835775-1	DB14S423D	SF2423-10B11	C	4835775-1	1.8°	1	p. 18	p. 22
42 mm sq.	DB14S424S	SF2424-10B41	C	4835775-1	DB14S424D	SF2424-10B11	C	4835775-1	1.8°	1	p. 18	p. 22
	DB16S141S	SH1421-5241	L	-	DB16S141D	SH1421-5211	L	-	0.9°	2	p. 18	p. 22
	DB16S142S	SH1422-5241	L	-	DB16S142D	SH1422-5211	L	-	0.9°	2	p. 18	p. 22
	DB16S144S	SH1424-5241	L	-	DB16S144D	SH1424-5211	L	-	0.9°	2	р. 19	p. 22
50 mm og	DB16H671S	103H6701-5040	L	-	DB16H671D	103H6701-5010	L	-	1.8°	2	р. 19	p. 23
oo min sq.	DB16H673S	103H6703-5040	L	-	DB16H673D	103H6703-5010	L	-	1.8°	2	р. 19	p. 23
	DB16M711S	SM2561C20B41	C	4837961-1	DB16M711D	SM2561C20B11	C	4837961-1	1.8°	2	р. 19	p. 23
E6 mm og	DB16M712S	SM2562C20B41	C	4837961-1	DB16M712D	SM2562C20B11	C	4837961-1	1.8°	2	p. 20	p. 23
oo min sq.	DB16M713S	SM2563C20B41	C	4837961-1	DB16M713D	SM2563C20B11	C	4837961-1	1.8°	2	p. 20	p. 23
	DB16M714S	SM2564C20B41	C	4837961-1	DB16M714D	SM2564C20B11	C	4837961-1	1.8°	2	p. 20	p. 23
60 mm ca	DB16S161S	SH1601-5240	L	-	DB16S161D	SH1601-5210	L	-	0.9°	2	p. 20	p. 23
oo min sq.	DB16S162S	SH1602-5240	L	-	DB16S162D	SH1602-5210	L	-	0.9°	2	p. 21	p. 23

• Motor cable with connectors Note: Included with connector-type motors only



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