

# 86 mm sq.

1.8°/step **RoHS**

Unipolar, lead type  
Bipolar, lead type ▶ p. 60



### Custom options

- Hollow shaft Custom shaft
- Encoder Brake

Note: Customization feasibility depends on the model number and quantity. Contact us for details.

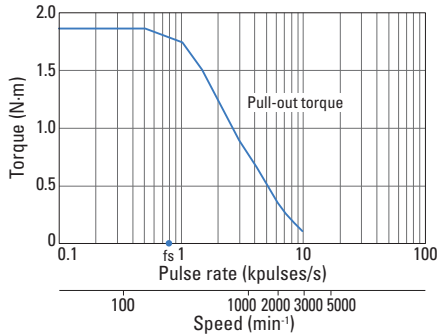
### Unipolar, lead type

Model no.		Holding torque at 2-phase excitation	Rated current	Winding resistance	Winding inductance	Rotor inertia	Mass	Motor length (L)
Single shaft	Dual shaft	N·m or more	A/phase	Ω/phase	mH/phase	×10 <sup>-4</sup> kg·m <sup>2</sup>	kg	mm
<b>SH2861-0441</b>	<b>SH2861-0411</b>	2.5	2	2.3	8.0	1.48	1.75	66
<b>SH2861-0941</b>	<b>SH2861-0911</b>	2.5	4	0.6	2.0	1.48	1.75	66
<b>SH2862-0441</b>	<b>SH2862-0411</b>	4.7	2	3.2	13.0	3.0	2.9	96.5
<b>SH2862-0941</b>	<b>SH2862-0911</b>	4.7	4	0.85	3.4	3.0	2.9	96.5
<b>SH2863-0441</b>	<b>SH2863-0411</b>	6.7	2	4.0	17.0	4.5	4.0	127
<b>SH2863-0941</b>	<b>SH2863-0911</b>	6.7	4	0.9	4.2	4.5	4.0	127

## Characteristics

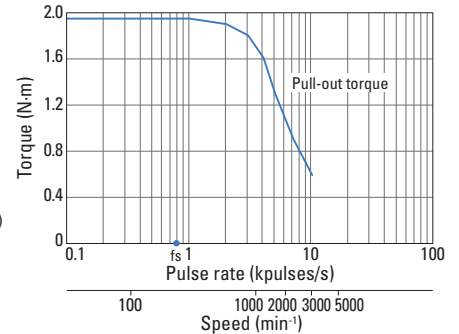
### SH2861-0441 SH2861-0411

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
2 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
 $f_s$ : Maximum starting pulse rate with no load



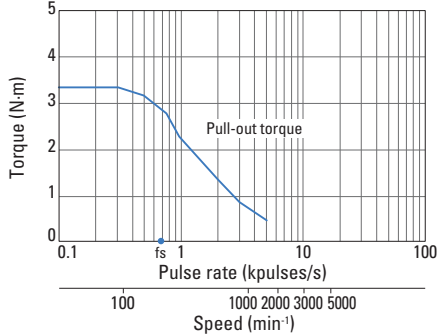
### SH2861-0941 SH2861-0911

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
4 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
 $f_s$ : Maximum starting pulse rate with no load



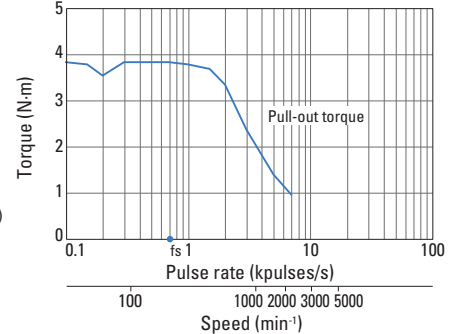
### SH2862-0441 SH2862-0411

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
2 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 15.3 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
 $f_s$ : Maximum starting pulse rate with no load



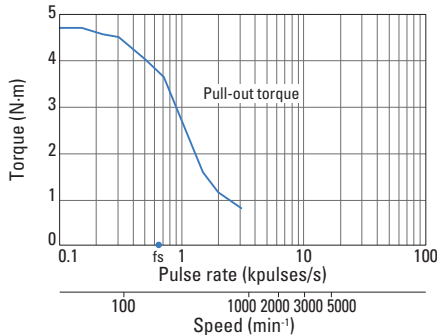
### SH2862-0941 SH2862-0911

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
4 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 15.3 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
 $f_s$ : Maximum starting pulse rate with no load



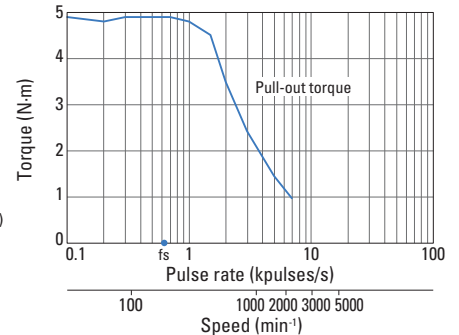
### SH2863-0441 SH2863-0411

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
2 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 15.3 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
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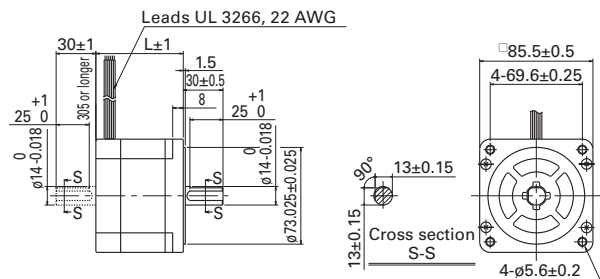
### SH2863-0941 SH2863-0911

Constant current circuit  
Input voltage: 100 VAC  
Winding current:  
4 A/phase  
At 2-phase excitation (full step)  
Pull-out torque:  
 $J_L = 15.3 \times 10^{-4} \text{kg}\cdot\text{m}^2$   
(with rubber coupling used)  
 $f_s$ : Maximum starting pulse rate with no load

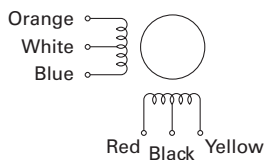


## Dimensions (Unit: mm)

### Lead type



## Internal winding



## Compatible drivers

A driver is to be provided by the customer.

DC Input Set Orders and Drivers

Stepping Motors

IP65-Rated Stepping Motors

In-Vacuum Stepping Motors

Synchronous Motors