

35 mm sq.

1.8°/step **RoHS**

Unipolar, lead type

Custom options

Hollow shaft Custom shaft

Note: Customization feasibility depends on the model number and quantity. Contact us for details.

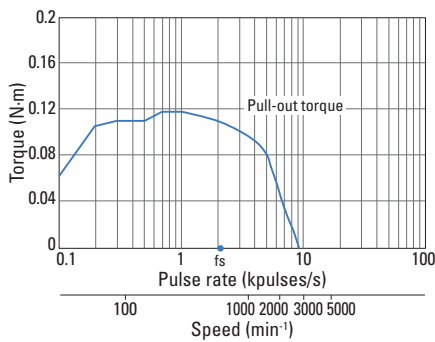
Unipolar, lead type

Model no.		Holding torque at 2-phase excitation	Rated current	Winding resistance	Winding inductance	Rotor inertia	Mass	Motor length (L)
Single shaft	Dual shaft	N·m or more	A/phase	Ω/phase	mH/phase	×10 ⁻⁴ kg·m ²	kg	mm
SH3533-12U40	SH3533-12U10	0.12	1.2	2.4	1.3	0.02	0.17	33
SH3537-12U40	SH3537-12U10	0.15	1.2	2.7	2	0.025	0.2	37
SH3552-12U40	SH3552-12U10	0.23	1.2	3.4	2.8	0.043	0.3	52

Characteristics

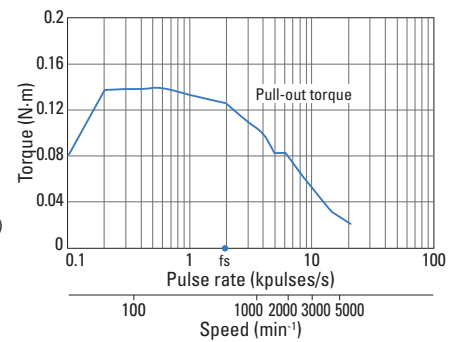
**SH3533-12U40
SH3533-12U10**

Constant current circuit
Input voltage: 24 VDC
Winding current: 1.2 A/phase
At 2-phase excitation (full step)
Pull-out torque:
 $J_r = 0.33 \times 10^{-4} \text{kg}\cdot\text{m}^2$
(with rubber coupling used)
 f_s : Maximum starting pulse rate with no load



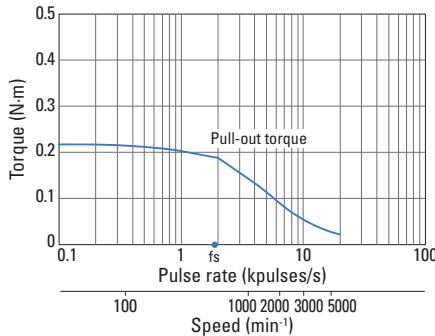
**SH3537-12U40
SH3537-12U10**

Constant current circuit
Input voltage: 24 VDC
Winding current: 1.2 A/phase
At 2-phase excitation (full step)
Pull-out torque:
 $J_r = 0.33 \times 10^{-4} \text{kg}\cdot\text{m}^2$
(with rubber coupling used)
 f_s : Maximum starting pulse rate with no load

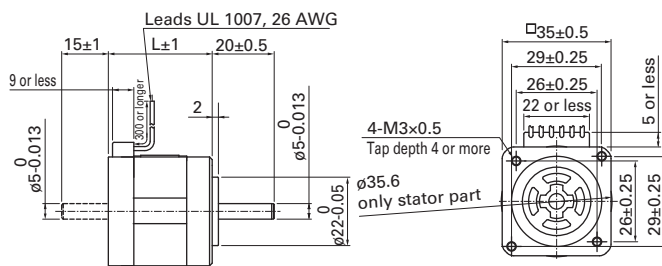


**SH3552-12U40
SH3552-12U10**

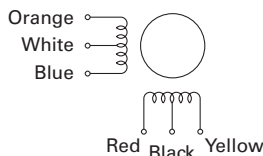
Constant current circuit
Input voltage: 24 VDC
Winding current: 1.2 A/phase
At 2-phase excitation (full step)
Pull-out torque:
 $J_r = 0.94 \times 10^{-4} \text{kg}\cdot\text{m}^2$
(with rubber coupling used)
 f_s : Maximum starting pulse rate with no load



Dimensions (Unit: mm)



Internal winding



Compatible drivers

Model no.: US1D200P10 (DC input)

Operating current selection switch setting: 8

Note: The characteristics shown above are calculated using our experimental circuit.